

## EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	742	trajector\$4 with pixel	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:47
L2	1569	382/103.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:47
L3	25	382/103.ccls. and trajector\$4 with pixel	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:54
L4	296	382/103.ccls. and (trajector\$4 or track\$4) with pixel	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:55
L5	163	382/103.ccls. and (trajector\$4 or track\$4) with pixel and vector	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:56
L6	22	382/103.ccls. and (trajector\$4 or track\$4) with pixel and vector with field	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 13:57
L7	12	382/103.ccls. and (trajector\$4 or track\$4) with pixel and vector near5 field	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:09

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L8	1012	348/169-172,208.14.ccls.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:01
L9	14	348/169-172,208.14.ccls.and (trajector\$4 or track\$4) with pixel and vector near5 field	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:06
L10	5	348/169-172,208.14.ccls.and (trajector\$4 or track\$4) with pixel and vector near5 field and optical near5 flow	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:06
L11	8	382/103.ccls. and (trajector\$4 or track\$4) with pixel and vector near5 field and optical with flow	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:11
L12	57	(trajector\$4 or track\$4) with pixel and vector near5 field and optical near4 flow	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2007/08/21 14:12


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## » Key

IEEE JNL IEEE Journal or Magazine

IET JNL IET Journal or Magazine

IEEE CNF IEEE Conference Proceeding

IET CNF IET Conference Proceeding

IEEE STD IEEE Standard

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- ☐ 1. Validation of an optical flow method for tag displacement estimation  
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